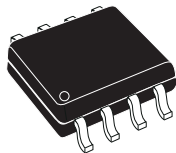


## 3.3 V powered, 15 kV ESD protected, up to 12 Mbps true RS-485/RS-422 transceiver



SO8

### Features

- ESD protection
  - –  $\pm 15$  kV human body model
  - –  $\pm 8$  kV IEC 1000-4-2 contact discharge
- Operates from a single 3.3 V supply - no charge pump required
- Interoperable with 5 V logic
- 1  $\mu$ A low current shutdown mode max.
- Guaranteed 12 Mbps data rate
- -7 to 12 common mode input voltage range
- Half duplex versions available
- Industry standard 75176 pinout
- Current limiting and thermal shutdown for driver overload protection
- Guaranteed high receiver output state for floating, shorted or terminated inputs with no signal present
- Allows up to 64 transceivers on the bus

### Description

The **ST1480US** is  $\pm 15$  kV ESD protected, 3.3 V low power transceiver for RS-485 and RS-422 communications. The device contains one driver and one receiver in half duplex configuration. The **ST1480US** transmits and receives at a guaranteed data rate of at least 12 Mbps. All transmitter outputs and receiver inputs are protected to  $\pm 15$  kV using human body model. Driver is short-circuit current limited and is protected against excessive power dissipation by thermal shutdown circuitry that places the driver outputs into a high-impedance state.

The **ST1480US** input has a true fail-safe feature that guarantees a logic high output if both inputs are open circuit, shorted together or in the presence of a termination with no signal on the bus.

Product status link

[ST1480US](#)

# 1 Pin configuration

Figure 1. Pin connections

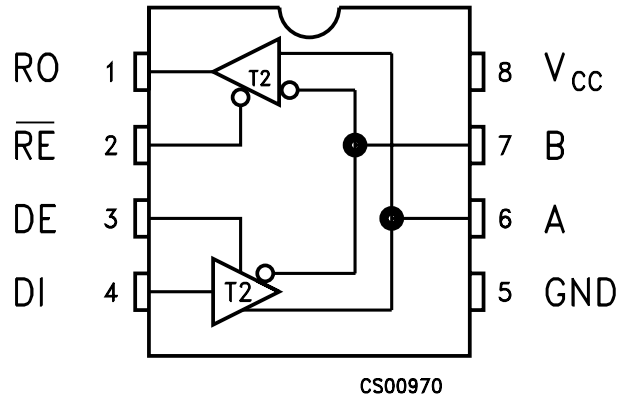


Table 1. Pin description

Pin	Symbol	Name and function
1	RO	Receiver output. If $A > B$ by 200 mV, RO is high; if $A < B$ by 200 mV, RO is low.
2	RE	Receiver output enable. RO is enabled when RE is low; RO is high impedance when RE is high. If RE is high and DE is low, the device enters a low power shutdown mode.
3	DE	Driver output enable. The driver outputs are enabled by bringing DE high. They are high impedance when DE is low. If RE is high DE is low, the device enters a low-power shutdown mode. If the driver outputs are enabled, the part functions as line driver, while they are high impedance, it functions as line receivers if RE is low.
4	DI	Driver input. A low on DI forces output A low and output B high. Similarly, a high on DI forces output A high and output B low.
5	GND	Ground
6	A	Non-inverting receiver input and non-inverting driver output.
7	B	Inverting receiver input and inverting driver output.
8	VCC	Supply voltage: $VCC = 3\text{ V to }3.6\text{ V}$ .

## 2 Truth tables

**Table 2. Truth table (driver)**

Inputs			Outputs		Mode
$\overline{RE}$	DE	DI	B	A	
X	H	H	L	H	Normal
X	H	L	H	L	Normal
L	L	X	Z	Z	Normal
H	L	X	Z	Z	Shutdown

Note: X= do not care; Z= high impedance

Inputs			Output	Mode
$\overline{RE}$	DE	A-B	RO	
L	L	$\geq +0.2V$	H	Normal
L	L	$\leq -0.2V$	L	Normal
L	L	Inputs open	H	Normal
L	L	Inputs shorted	H	Normal
H	L	X	Z	Shutdown

Note: X= do not care; Z= high impedance

### 3 Maximum ratings

**Table 3. Absolute maximum ratings**

Symbol	Parameter		Value	Unit
$V_{CC}$	Supply voltage		7	V
$V_I$	Control input voltage ( $\overline{RE}$ , DE)		-0.3 to 7	V
$V_{DI}$	Driver input voltage (DI)		-0.3 to 7	V
$V_{DO}$	Driver output voltage (A, B)		$\pm 14$	V
$V_{RI}$	Receiver input voltage (A, B)		$\pm 14$	V
$V_{RO}$	Receiver output voltage (RO)		-0.3 to ( $V_{CC} + 0.3$ )	V
ESD	ESD protection voltage	Human body model	$\pm 15$	kV
		IEC-1000-4-2 contact discharge	$\pm 8$	

*Note:* Absolute maximum ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied.

## 4 Electrical characteristics

$V_{CC} = 3\text{ V to }3.6\text{ V}$ ,  $T_A = -40\text{ to }85\text{ }^\circ\text{C}$ , unless otherwise specified. Typical values are referred to  $T_A = 25\text{ }^\circ\text{C}$ ).

**Table 4. Electrical characteristics**

Symbol	Parameter	Test conditions		Min.	Typ.	Max.	Unit
$I_{SUPPLY}$	$V_{CC}$ power supply current	No Load, DI = 0 V or $V_{CC}$	DE = $V_{CC}$ , $\overline{RE} = 0\text{ V or }V_{CC}$		1.3	2.2	mA
			DE=0 V, $\overline{RE}=0\text{ V}$		1.2	1.9	mA
$I_{SHDN}$	Shutdown supply current	DE = 0 V, RE = $V_{CC}$ , DI = 0 V or $V_{CC}$			0.002	1	$\mu\text{A}$

**Table 5. Logic input electrical characteristics**

Symbol	Parameter	Test conditions		Min.	Typ.	Max.	Unit
$V_{IL}$	Input logic threshold low	DE, DI, RE				0.8	V
$V_{IH}$	Input logic threshold high	DE, DI, RE		2			V
$I_{IN1}$	Logic input current	DE, DI, RE				$\pm 2.0$	$\mu\text{A}$
$I_{IN2}$	Input current (A, B)	DE=0 V, $V_{CC}=0$ or 3.6 V	VIN = 12 V			1	mA
			VIN = -7 V			-0.8	mA

**Table 6. Transmitter electrical characteristics**

Symbol	Parameter	Test conditions		Min.	Typ.	Max.	Unit
$V_{OD}$	Differential drive output	$R_L = 100\ \Omega$ (RS-422) (Figure 1. Pin connections)		2			V
		$R_L = 54\ \Omega$ (RS-485) (Figure 1. Pin connections)		1.5			V
		$R_L = 60\ \Omega$ (RS-485) (Figure 2. Driver and $V_{OC}$ test load)		1.5			V
$\Delta V_{OD}$	Change in magnitude of driver differential output voltage for complementary output states <sup>(1)</sup>	$R_L = 54\ \Omega$ or $100\ \Omega$ (Figure 1. Pin connections)				0.2	V
$V_{OC}$	Driver common mode output voltage	$R_L = 54\ \Omega$ or $100\ \Omega$ (Figure 1. Pin connections)				3	V
$\Delta V_{OC}$	Change in magnitude of driver common mode output voltage <sup>(1)</sup>	$R_L = 54\ \Omega$ or $100\ \Omega$ (Figure 1. Pin connections)				0.2	V
$I_{OSD}$	Driver short-circuit output current					$\pm 250$	mA

1.  $\Delta V_{OD}$  and  $\Delta V_{OC}$  are the changes in  $V_{OD}$  and  $V_{OC}$ , respectively, when the DI input changes state.

**Table 7. Receiver electrical characteristics**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$V_{TH}$	Receiver differential threshold voltage	$V_{CM} = -7\text{ V to } 12\text{ V}$ , $DE = 0$	-0.2		-0.015	V
$\Delta V_{TH}$	Receiver input hysteresis	$V_{CM} = 0\text{ V}$		30		$\mu\text{V}$
$V_{OH}$	Receiver output high voltage	$I_{OUT} = -4\text{ mA}$ , $V_{ID} = 200\text{ mV}$ , (Figure 8. Drive enable and disable times waveforms)	2			V
$V_{OL}$	Receiver output low voltage	$I_{OUT} = 4\text{ mA}$ , $V_{ID} = -200\text{ mV}$ , (Figure 3. Driver $V_{OD}$ with varying common mode voltage test load)			0.4	V
$I_{OZR}$	3-state (high impedance) output current at receiver	$V_{CC} = 3.6\text{ V}$ , $V_O = 0\text{ V to } V_{CC}$			$\pm 1$	$\mu\text{A}$
$R_{RIN}$	Receiver input resistance	$V_{CM} = -7\text{ V to } 12\text{ V}$	24			$\text{k}\Omega$
$I_{OSR}$	Receiver short-circuit current	$V_{RO} = 0\text{ V to } V_{CC}$	7		60	mA

**Table 8. Driver switching characteristics**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$D_R$	Maximum data rate		12	15		Mbps
$t_{DD}$	Differential output delay	$R_L = 60\ \Omega$ , $C_L = 15\text{ pF}$ , (Figure 4. Receiver $V_{OH}$ and $V_{OL}$ test circuit and Figure 5. Drive differential output delay transition time test circuit)		18	30	ns
$t_{TD}$	Differential output transition time	$R_L = 60\ \Omega$ , $C_L = 15\text{ pF}$ , (Figure 4. Receiver $V_{OH}$ and $V_{OL}$ test circuit and Figure 5. Drive differential output delay transition time test circuit)		12	20	ns
$t_{PLH}$ $t_{PHL}$	Propagation delay	$R_L = 27\ \Omega$ , $C_L = 15\text{ pF}$ , (Figure 8. Drive enable and disable times waveforms and Figure 9. Drive propagation time test circuit)		18	30	ns
$t_{PDS}$	$ t_{PLH} - t_{PHL} $ propagation delay skew <sup>(1)</sup>	$R_L = 27\ \Omega$ , $C_L = 15\text{ pF}$ , (Figure 8. Drive enable and disable times waveforms and Figure 9. Drive propagation time test circuit)		2	5	ns
$t_{PZL}$	Output enable time	$R_L = 110\ \Omega$ , (Figure 10. Drive propagation time waveform and Figure 11. Drive enable and disable times test circuit ( $R_L = 110\ \Omega$ ))		19	35	ns
$t_{PZH}$	Output enable time	$R_L = 110\ \Omega$ , (Figure 10. Drive propagation time waveform and Figure 11. Drive enable and disable times test circuit ( $R_L = 110\ \Omega$ ))		30	50	ns
$t_{PHZ}$	Output disable time	$R_L = 110\ \Omega$ , (Figure 6. Drive differential output delay transition time waveform and Figure 7. Drive enable and disable times test circuit)		19	35	ns
$t_{PLZ}$	Output disable time	$R_L = 110\ \Omega$ (Figure 10. Drive propagation time waveform and Figure 11. Drive enable and disable times test circuit ( $R_L = 110\ \Omega$ ))		30	50	ns
$t_{SKEW}$	Differential output delay skew			1	3	ns
$t_{ZH(SHDN)}$	Driver enable from shutdown to output high			30	50	ns
$t_{ZL(SHDN)}$	Driver enable from shutdown to output low			19	35	ns

 1. Measured on  $|t_{PLH(A)} - t_{PHL(A)}|$  and  $|t_{PLH(B)} - t_{PHL(B)}|$

**Table 9. Receiver switching characteristics**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation delay	V <sub>ID</sub> = 0 V to 3 V, C <sub>L1</sub> =15 pF (Figure 12. Drive enable and disable times waveforms (B) and Figure 13. Receiver propagation delay time test circuit)		30	50	ns
t <sub>RPDS</sub>	t <sub>PLH</sub> - t <sub>PHL</sub>   propagation delay skew	V <sub>ID</sub> = 0 V to 3 V, C <sub>L1</sub> =15 pF (Figure 12. Drive enable and disable times waveforms (B) and Figure 13. Receiver propagation delay time test circuit)		1	3	ns
t <sub>PZL</sub>	Outputenable time	C <sub>RL</sub> = 15 pF, (Figure 14. Receiver propagation delay time waveforms and Figure 18. Receiver enable and disable times waveform (S2 closed))		10	20	ns
t <sub>PZH</sub>	Outputenable time	C <sub>RL</sub> = 15 pF, (Figure 14. Receiver propagation delay time waveforms and Figure 18. Receiver enable and disable times waveform (S2 closed))		10	20	ns
t <sub>PHZ</sub>	Outputdisable time	C <sub>RL</sub> = 15 pF, (Figure 14. Receiver propagation delay time waveforms and Figure 18. Receiver enable and disable times waveform (S2 closed))		10	20	ns
t <sub>PLZ</sub>	Outputdisable time	C <sub>RL</sub> = 15 pF, (Figure 14. Receiver propagation delay time waveforms and Figure 18. Receiver enable and disable times waveform (S2 closed))		10	20	ns
t <sub>ZH(SHDN)</sub>	Receiver enable from shutdown to output high	C <sub>RL</sub> = 15 pF, (Figure 14. Receiver propagation delay time waveforms and Figure 18. Receiver enable and disable times waveform (S2 closed))		10	20	ns
t <sub>ZL(SHDN)</sub>	Receiver enable from shutdown to output low	C <sub>RL</sub> = 15 pF, (Figure 14. Receiver propagation delay time waveforms and Figure 18. Receiver enable and disable times waveform (S2 closed))		20	40	μs

## 5 Test circuits and typical characteristics

Figure 2. Driver and  $V_{OC}$  test load

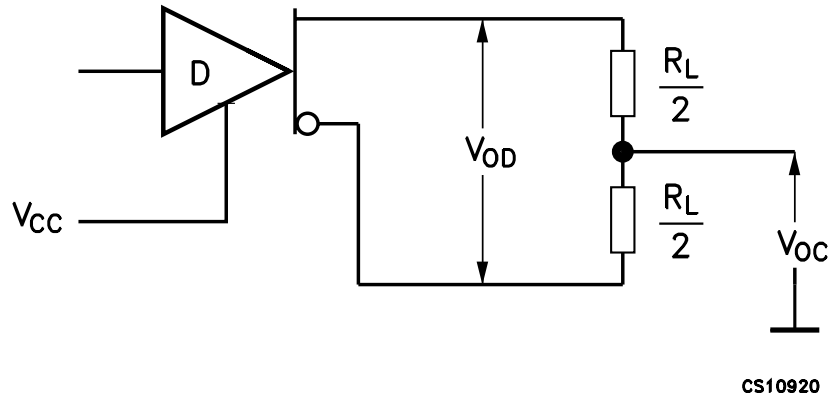


Figure 3. Driver  $V_{OD}$  with varying common mode voltage test load

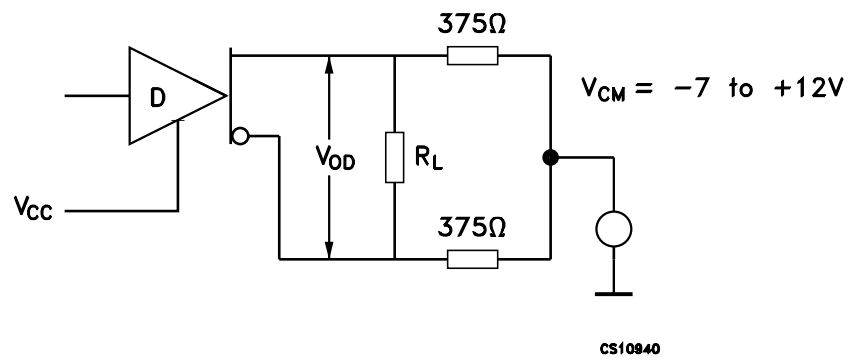


Figure 4. Receiver  $V_{OH}$  and  $V_{OL}$  test circuit

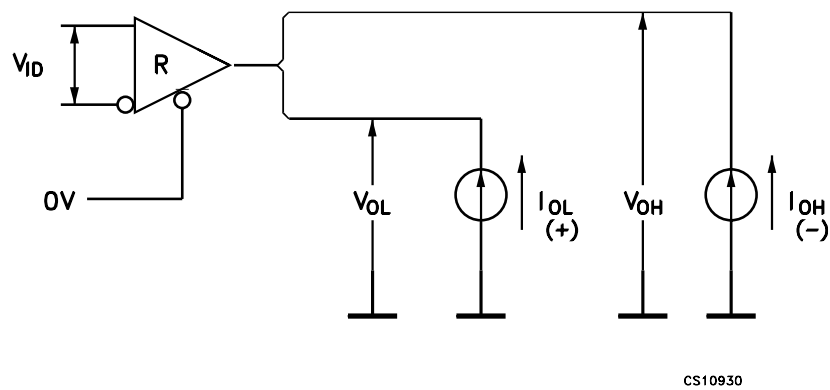




Figure 5. Drive differential output delay transition time test circuit

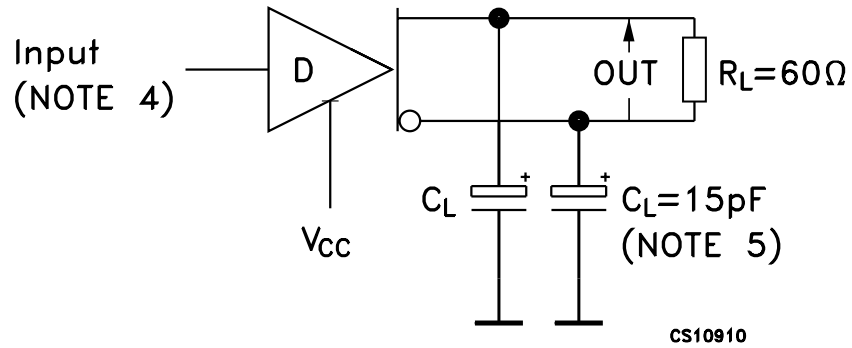


Figure 6. Drive differential output delay transition time waveform

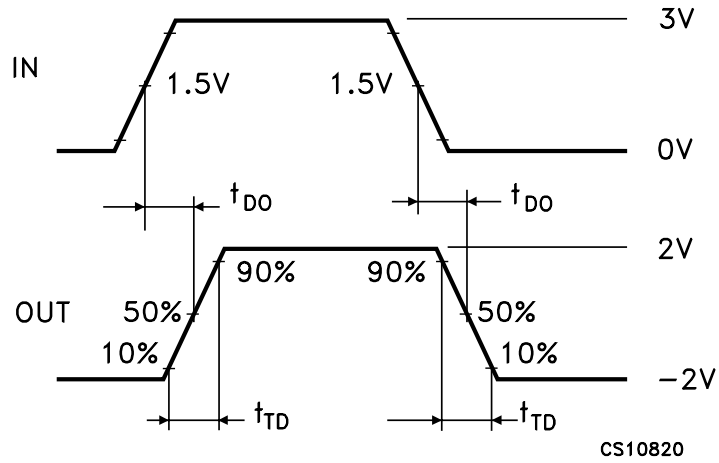
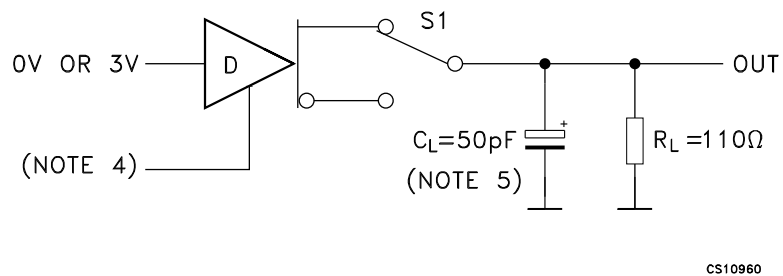


Figure 7. Drive enable and disable times test circuit



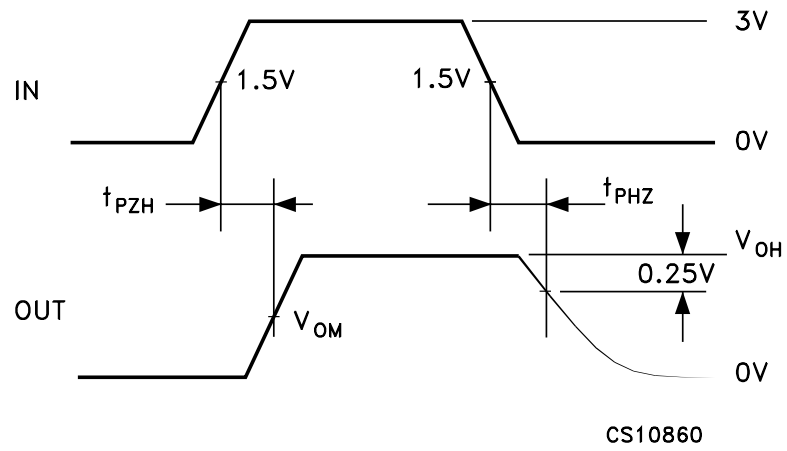
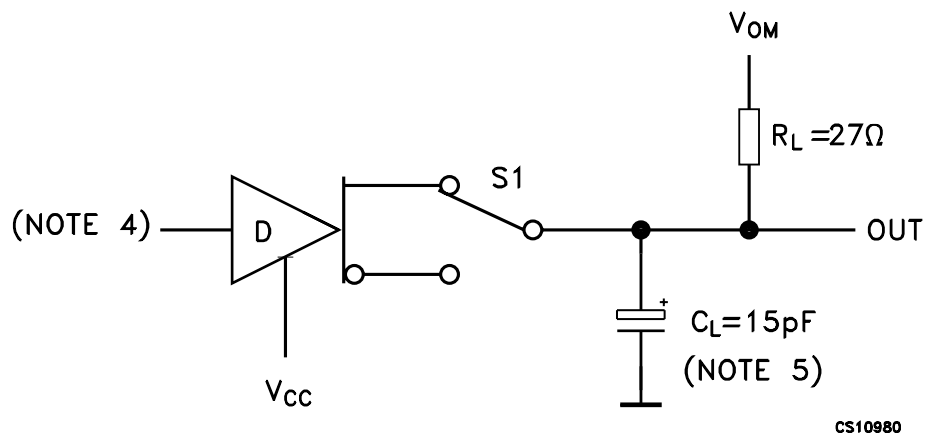
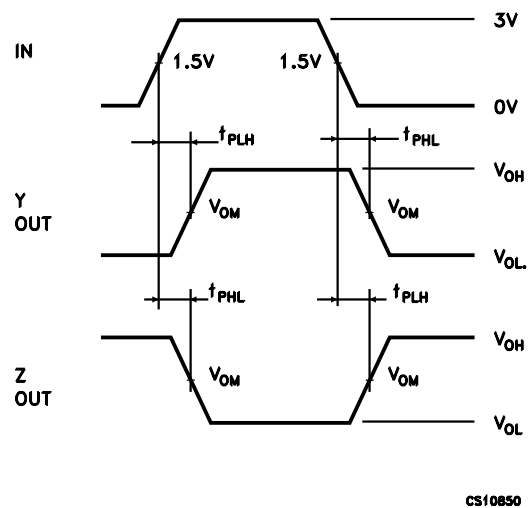
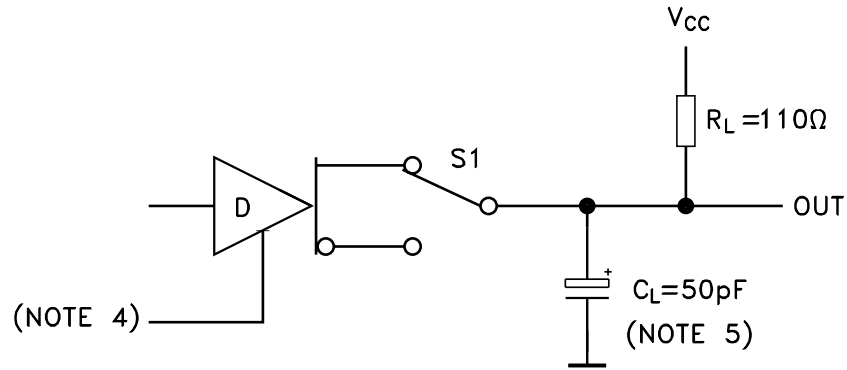
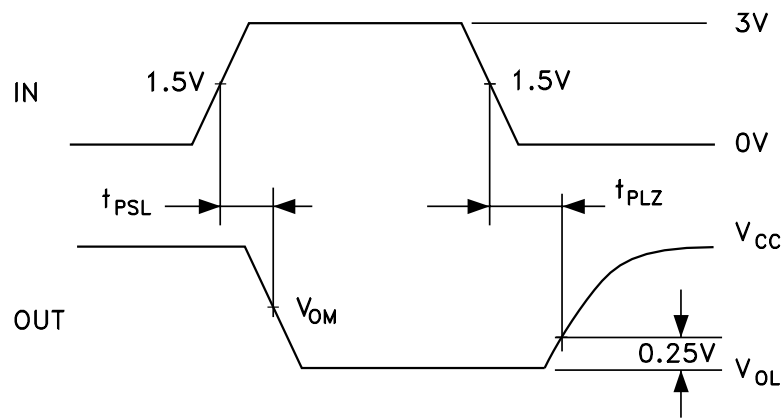
**Figure 8. Drive enable and disable times waveforms**

**Figure 9. Drive propagation time test circuit**

**Figure 10. Drive propagation time waveform**


Figure 11. Drive enable and disable times test circuit ( $R_L = 110 \Omega$ )



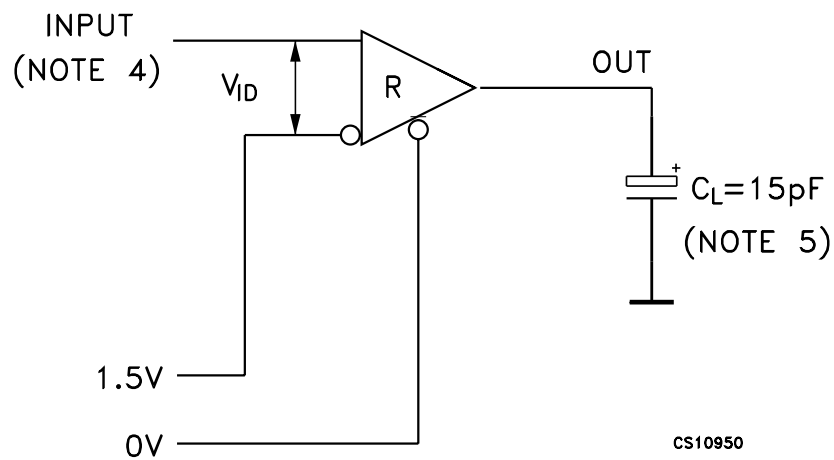
CS10970

Figure 12. Drive enable and disable times waveforms (B)

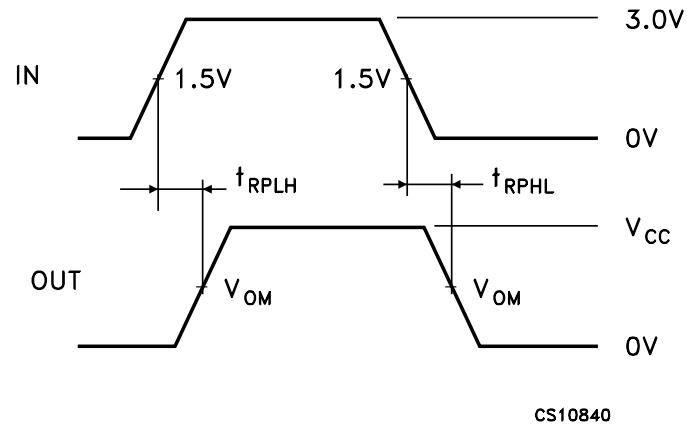
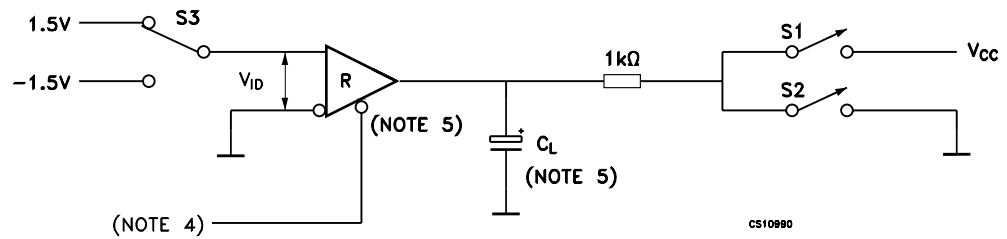
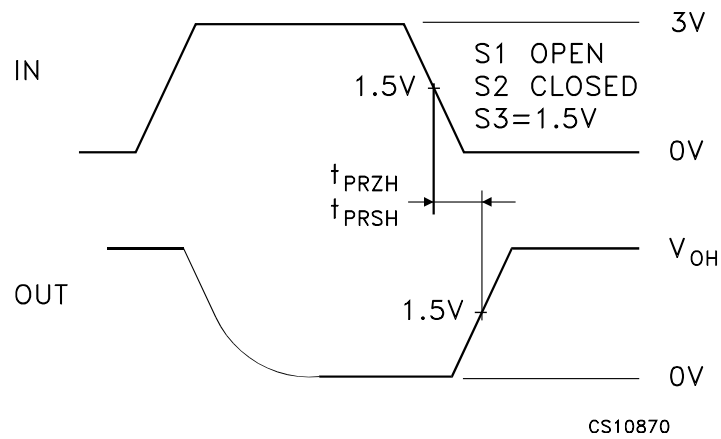


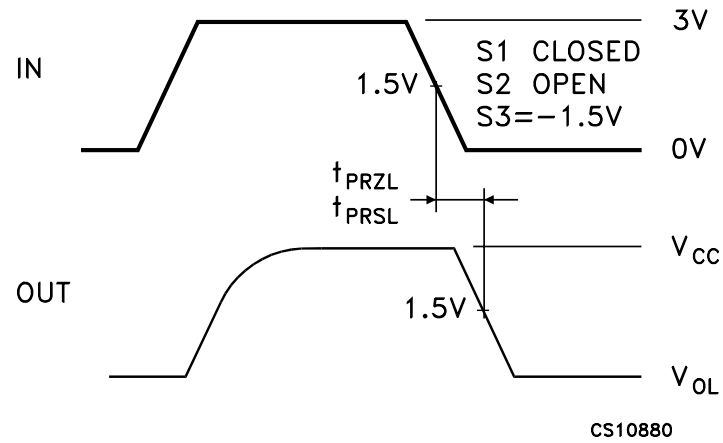
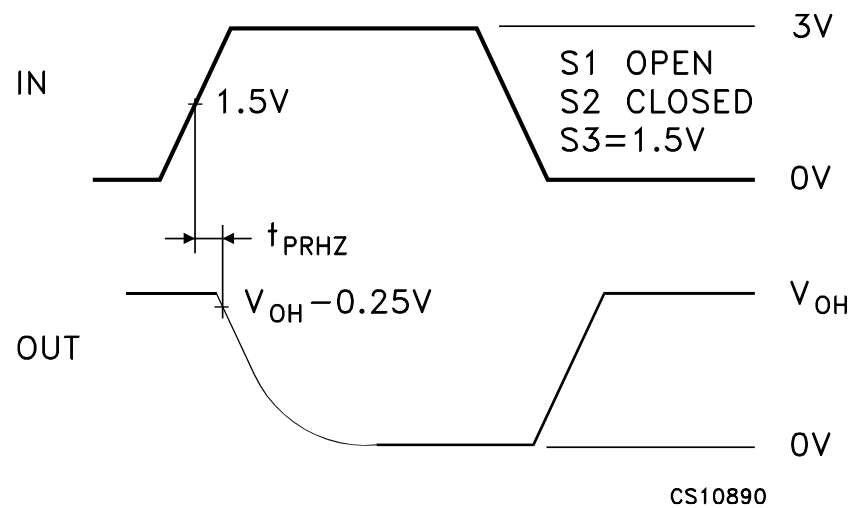
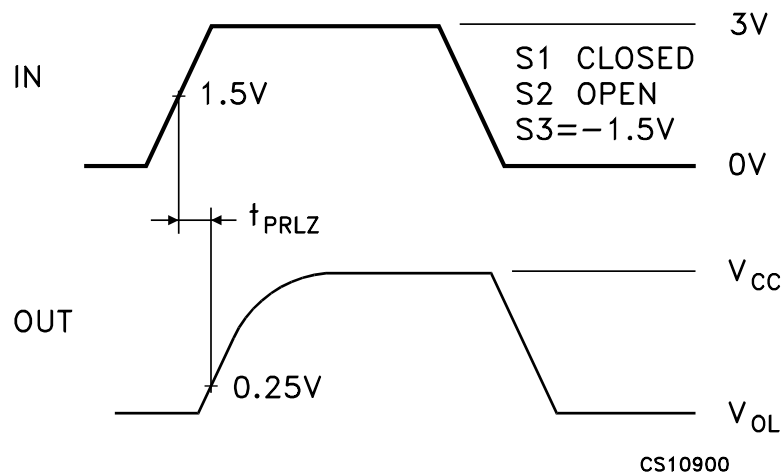
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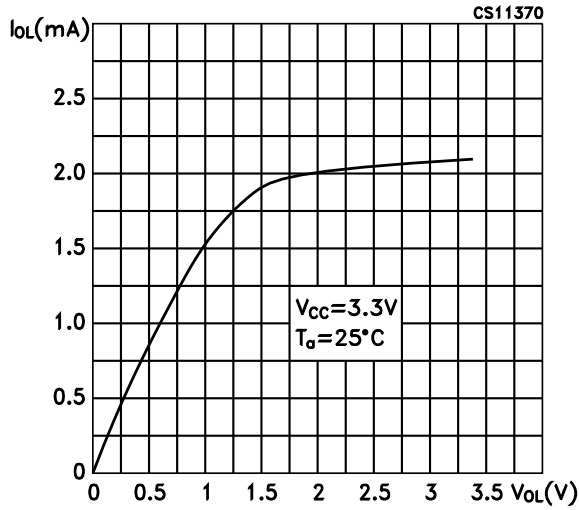
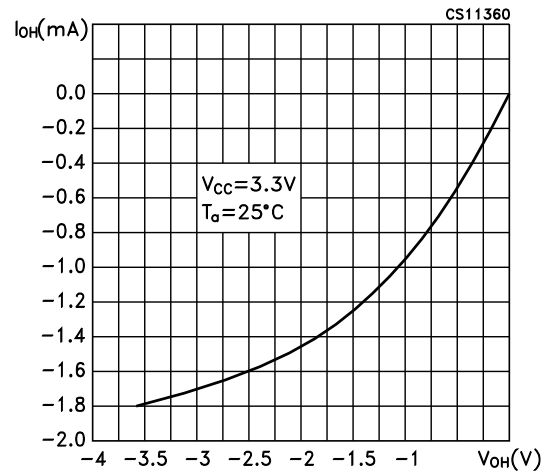
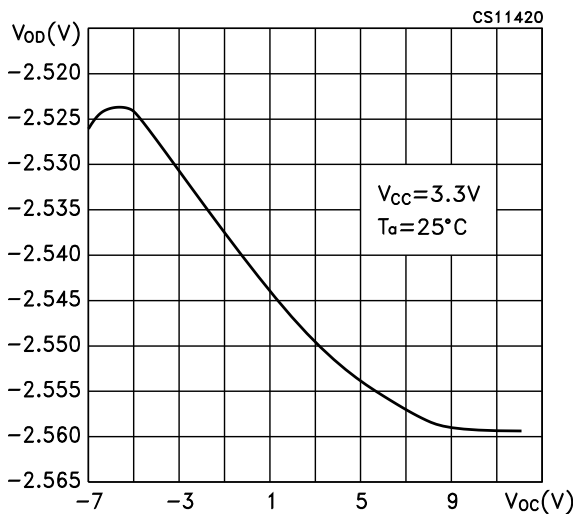
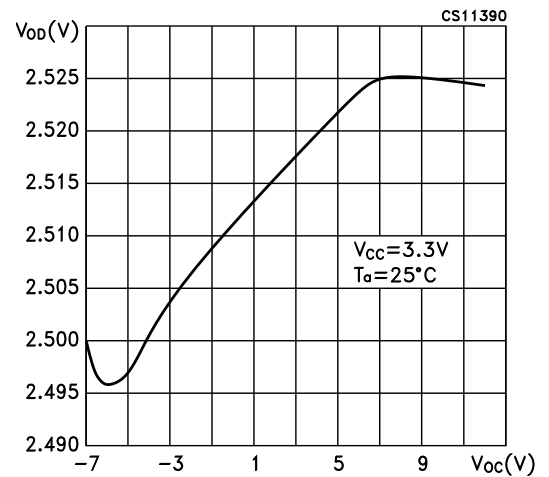
Figure 13. Receiver propagation delay time test circuit

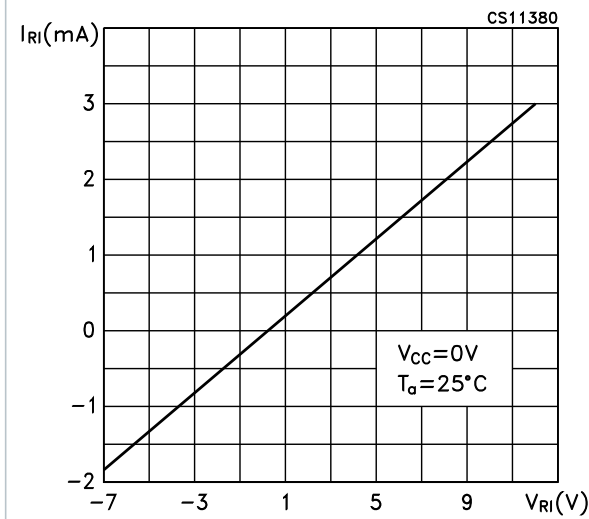
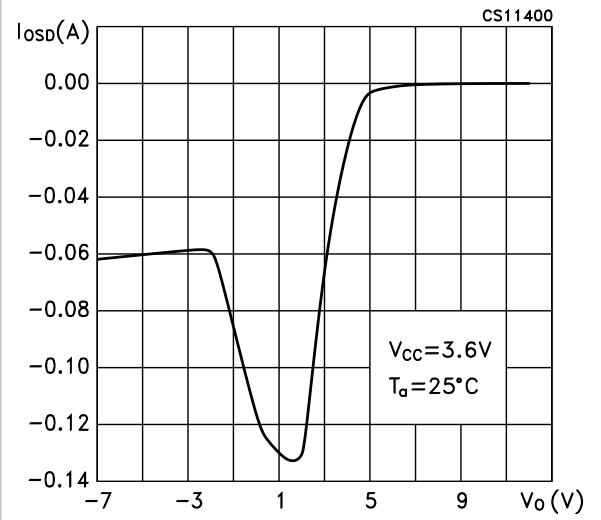
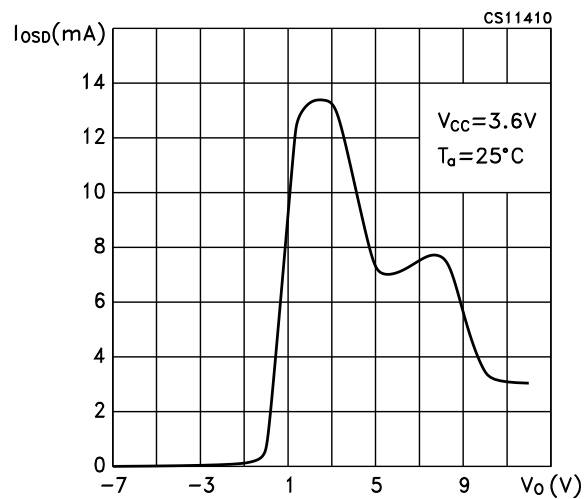


CS10950

**Figure 14. Receiver propagation delay time waveforms**

**Figure 15. Receiver enable and disable times test circuit (B)**

**Figure 16. Receiver enable and disable times waveform (S1 open)**


**Figure 17. Receiver enable and disable times waveform (S1 closed)**

**Figure 18. Receiver enable and disable times waveform (S2 closed)**

**Figure 19. Receiver enable and disable times waveform (S2 open)**


**Figure 20. Receiver output current vs. output low voltage**

**Figure 21. Receiver output current vs. output high voltage**

**Figure 22. Low level driver output capability**

**Figure 23. High level driver output capability**


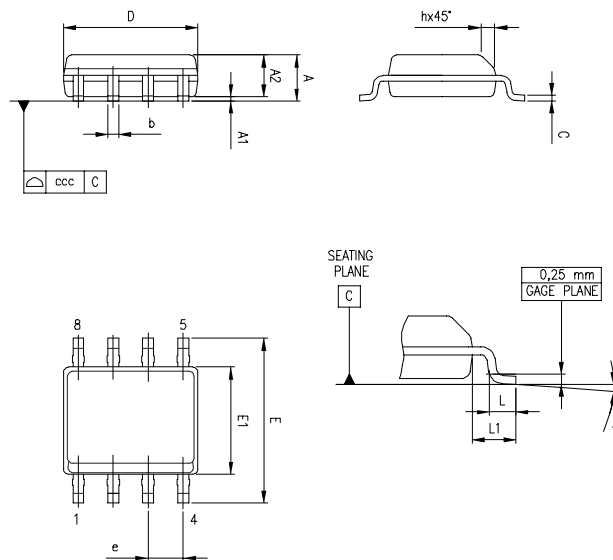
**Figure 24. Receiver input characteristics**

**Figure 25. Driver short-circuit current**

**Figure 26. Driver short-circuit current**


## 6 Package information

In order to meet environmental requirements, ST offers these devices in different grades of **ECOPACK** packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at: [www.st.com](http://www.st.com). ECOPACK is an ST trademark.

### 6.1 SO8 package information

**Figure 27. SO8 package outline**



**Table 10. SO-8 mechanical data**

Dim.	mm			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A			1.75			0.069
A1	0.1		0.25	0.004		0.01
A2	1.25			0.049		
b	0.28		0.48	0.011		0.019
c	0.17		0.23	0.007		0.01
D	4.8	4.9	5	0.189	0.193	0.197
E	5.8	6	6.2	0.228	0.236	0.244
E1	3.8	3.9	4	0.15	0.154	0.157
e		1.27			0.05	
h	0.25		0.5	0.01		0.02
L	0.4		1.27	0.016		0.05
L1		1.04			0.04	
k	0		8 °	1 °		8 °
ccc			0.1			0.004



## 7 Ordering information

**Table 11. Ordering information**

Order codes	Temperature range	Package	Packing
ST1480ACDR/US	0 to 70 °C	SO-8 tape and reel	2500 parts per reel

## Revision history

**Table 12. Document revision history**

Date	Version	Changes
06-Apr-2021	1	Initial release.

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